# Morse-Bott Functions from Moment Maps

Reto Kaufmann E-mail: reto.kaufmann@math.ethz.ch

November 3, 2022

## Contents

1	Morse-Bott Functions	1
2	Morse-Bott Functions from Moment Maps	<b>2</b>
3	Application: Preimage of a Facet of a Moment Polytope	3

#### **1** Morse-Bott Functions

We follow the definitions and presentation of [2].

Let M be a smooth manifold,  $f: M \to \mathbb{R}$  a smooth function and  $\operatorname{Crit}(f) = \{p \in M \mid df_p = 0\}$ its set of critical points.

**Definition.** The Hessian  $H_p(f)$  of f at a critical point  $p \in Crit(f)$  is the symmetric bilinear form given by

$$[\mathrm{H}_p(f)](X_p, Y_p) = X_p(Y(f))$$

where  $X_p, Y_p \in T_pM$  are tangent vectors and  $Y \in \mathfrak{X}(M)$  is any vector field on M such that  $Y(p) = Y_p$ .

If  $C \subset \operatorname{Crit}(f)$  is a submanifold of positive dimension, for any  $Y \in \mathfrak{X}(M)$  we have  $Y(f)|_C = df(Y)|_C = 0$ . Hence if  $X_p \in T_pC$  it follows that

$$[\mathrm{H}_p(f)](X_p, Y_p) = X_p(Y(f)) = 0$$

and thus  $T_pC \subset \ker(\mathrm{H}_p(f))$ .

**Definition.**  $f: M \to \mathbb{R}$  is called a *Morse-Bott function* if

- 1.  $\operatorname{Crit}(f)$  is a disjoint union of connected submanifolds and
- 2. for each connected submanifold  $C \subset \operatorname{Crit}(f)$  and each  $p \in C$  we have  $\ker(\operatorname{H}_p) = T_p C$ .

**Remark.** The non-degeneracy condition can be equivalently phrased as follows: Denote  $\nu C$  the normal bundle of C with fiber  $\nu_p C = T_p M/T_p C$  at  $p \in C$ . Note that from a(ny) Riemannian metric on M we get a splitting

$$TM|_C = TC \oplus \nu C.$$

As  $T_pC \subset \ker(\operatorname{H}_p(f))$ ,  $\operatorname{H}_p(f)$  induces a symmetric bilinear form  $\operatorname{H}_p^{\nu}(f)$  on  $\nu_pC$ . The non-degeneracy condition is then equivalent to  $\operatorname{H}_p^{\nu}(f)$  being non-degenerate for all  $p \in C$ .

**Lemma** (Morse-Bott Lemma). Let  $f : M \to \mathbb{R}$  be a Morse-Bott function and  $C \subset Crit(f)$  be a connected component. For any  $p \in C$  there is a local chart of M around p and a local splitting  $\nu C = \nu^{-}C \oplus \nu^{+}C$  identifying a point  $q \in M$  with (u, v, w) where  $u \in C$ ,  $v \in \nu^{-}C$  and  $w \in \nu^{+}C$  such that within this chart f assumes the form

$$f(q) = f(u, v, w) = f(C) - |v|^2 + |w|^2.$$

**Definition.** The Morse-Bott index of a connected component C is the dimension of  $\nu^-C$ .

**Example.** Consider the height function  $f: T \to \mathbb{R}$  on the laying doughnut. This is a Morse-Bott function with two critical submanifolds, both isomorphic to  $S^1$ . The circle on top has Morse-Bott index 1 and the circle on the bottom has Morse-index 0.

**Example.** Consider the square  $f = h^2 : S^n \to \mathbb{R}$  of height function  $h : S^n \to \mathbb{R}$ . This is a Morse-Bott function with 3 critical submanifolds: the north and southpole have dimension 0 but the equator is sphere of dimension n-1 i.e.  $S^{n-1}$ . The north pole and the southpole have index n while the equator has index 0.

#### 2 Morse-Bott Functions from Moment Maps

**Theorem.** Let G be a compact Lie group and let  $(M, \omega, G, \mu)$  be a hamiltonian G-space. For any  $X \in \mathfrak{g}$ , the component of  $\mu$  along X given by

$$\mu^X : M \to \mathbb{R}$$
$$p \mapsto \mu^X(p) = \langle \mu(p), X \rangle$$

is a Morse-Bott function and the critical manifolds are symplectic submanifolds and the indices are all even.

*Proof.* (Inspired by [4], Theorem 2.2)  $X \in \mathfrak{g}$  generates a one-parameter subgroup of G. Its closure is connected, compact since G is and Abelian. Thus it is a torus  $\mathcal{T} < G$  of some dimension. By

definition of the moment map,  $d\mu^X = -\iota_X \sharp \omega$  so that for any  $p \in M$ 

$$p \in \operatorname{Crit} (\mu^X) \qquad \Longleftrightarrow \qquad \operatorname{d} (\mu^X)_p = 0$$
$$\iff \qquad -\iota_{X_p^{\sharp}} \omega_p = 0$$
$$\iff \qquad X_p^{\sharp} = 0$$
$$\iff \qquad p \in M^{\mathcal{T}}.$$

or in other words,

$$\operatorname{Crit}\left(\mu^{X}\right) = M^{\mathcal{T}}.$$

We thus conclude that the connected components of Crit  $(\mu^X)$  are symplectic submanifolds.

To see the non-degeneracy, we look at the moment map  $\mu$  in a neighbourhood of a point  $p \in M^{\mathcal{T}}$ in its local form of the Toric Darboux Theorem

$$\mu = \mu(p) + \frac{1}{2} \sum_{i=1}^{n} |z_i|^2 \lambda^{(i)},$$

where the  $\lambda^{(i)}$  are the weights of the isotropy representation. Evaluating at X gives the candidate for the Morse-Bott function in these local coordinates:

$$\mu^{X} = \langle \mu(p), X \rangle + \frac{1}{2} \sum_{i=1}^{n} |z_{i}|^{2} \left\langle \lambda^{(i)}, X \right\rangle.$$

If  $\langle \lambda^{(i)}, X \rangle = 0$  then it follows by continuity of the action and the fact that  $\exp(\mathbb{R}X)$  is dense in  $\mathcal{T}$  that the *i*-th summand  $V_i$  in  $T_p M$  is fixed by  $\mathcal{T}$ . It follows that

$$(T_p M)^{\mathcal{T}} = \bigoplus_{i:\,\lambda^{(i)}=0} V_i = \bigoplus_{i:\,\langle\lambda^{(i)},X\rangle=0} V_i = \ker(\mu^X).$$

But since we can identify  $T_p(M^{\mathcal{T}}) = (T_pM)^{\mathcal{T}}$ , this is exactly the non-degeneracy condition. Since  $|z_i|^2 = x_i^2 + y_i^2$  we also conclude that all the indices are even.

# 3 Application: Preimage of a Facet of a Moment Polytope

**Theorem** (Atiyah, Guillemin-Sternberg). Let  $(M, \omega, \mathcal{T}, \mu)$  be a compact connected Hamiltonian  $\mathcal{T}$ -space for a torus  $\mathcal{T}$ . Then:

- 1. the levels of  $\mu$  are connected;
- 2. the image of  $\mu$  is convex;
- 3. the image of  $\mu$  is the convex hull of a finite number of points, that are images of the fixed points of the action.

*Proof.* See e.g. the paper by Atiyah [1] or the one by Guillemin Sternberg [3].

Let  $\Delta$  be the moment polytope of a Hamiltonian  $\mathcal{T}$ -space M:

$$\mu(M) = \Delta = \bigcap_{i \in \mathcal{I}} \mathbb{H}_{(v_i, c_i)} = \{ \varphi \in \mathfrak{t}^* \mid \langle \varphi, v_i \rangle \le c_i \quad \text{for all} \quad i \in \mathcal{I} \}$$

Let F be a facet of  $\Delta$ , that is, there is a  $j \in \mathcal{I}$  such that

$$F = \{\varphi \in \Delta \mid \langle \varphi, v_j \rangle = c_j \}$$

and consider its preimage under the moment map  $N := \mu^{-1}(F)$ . Since  $\mu$  is continuous and F is closed, N is closed.

 $v_j$  determines an  $S^1$ -subgroup of  $\mathcal{T}$  which also acts Hamiltonian way on M with moment map  $i^* \circ \mu$ , where  $i : \mathfrak{s} \hookrightarrow \mathfrak{t}$  is the inclusion. We get

$$\langle i^* \circ \mu(p), v \rangle = \langle \mu(p), i(v) \rangle = \langle \mu(p), v \rangle.$$

But  $\mu(p) \in \Delta$  so that

$$\langle \mu(p), v_j \rangle = c_j \iff \mu(p) \in F \iff p \in N$$

which shows that N is a level set of  $d_e^* \circ \mu$ . Therefore, by the convexity Theorem N is connected.

We know that  $(i^* \circ \mu)^{v_j}$  is a Morse-Bott function and the connected components of Crit  $((i^* \circ \mu)^{v_j})$ are thus symplectic submanifolds. N is by construction such a critical submanifold of  $(i^* \circ \mu)^{v_j}$ . This shows that it is a symplectic submanifold of M.

## References

- Michael Francis Atiyah. Convexity and commuting hamiltonians. Bulletin of the London Mathematical Society, 14(1):1–15, 1982.
- [2] Augustin Banyaga and David E Hurtubise. Cascades and perturbed morse-bott functions. Algebraic & Geometric Topology, 13(1):237-275, feb 2013.
- [3] Victor Guillemin and Shlomo Sternberg. Convexity properties of the moment mapping. *Inven*tiones mathematicae, 67(3):491–513, 1982.
- [4] Eckhard Meinrenken. Symplectic geometry. Lecture Notes, University of Toronto, 2000.